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2015



Wearable Sensor Data and Medical Records for Clinical Outcome Prediction

Gina Sprint, CS PhD Student Washington State University October 14th, 2015



Wearables for Rehabilitation

- Why technology for rehabilitation?
 - Fine-grained, objective data
- Why wearable sensors?

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- Portable, inexpensive, unobtrusive,
- Why ecological environments?
 - More representative of abilities
 - Resembles discharge environment

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Ambulation Circuit (AC)



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AC Study Participants

- N=20 (M=14, F=6)
- 71.55 ± 10.62 years of age
- Stroke, brain injury, debility, cardiac, etc.
- 2 Testing sessions
 - 1 Week apart

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Data Processing



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Clinical Outcome Prediction

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Functional Independence
Measure (FIM)

- Measured at admission and discharge
- 13 Motor tasks Motor
 - Transfers

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- Locomotion
- 5 Cognitive tasks
- Utilize additional patient medical records (N=4936) for training (NAC dataset)

Task Type	#	Task
	1	Eating
	2	Grooming
	3	Bathing
	4	Upper body dressing
	5	Lower body dressing
	6	Toileting
Motor	7	Bladder management
	8	Bowel management
	9	Bed to chair transfer
	10	Toilet transfer
	11	Shower transfer
	12	Locomotion (ambulatory or wheelchair level)
	13	Stairs
	14	Cognitive comprehension
	15	Expression
 Cognitive 	16	Social interaction
	17	Problem solving
	18	Memory

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Medical Record Features

- Patient characteristics
 - Age

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- Gender
- Rehabilitation impairment category (RIC)
- Comorbidity tier
- Case mix group (accounts for medical complications)
- Admission Functional Independence Measure (FIM)
 - Individual tasks

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- Motor aggregate score
- Cognitive aggregate score



AC Features

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Gait

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- Velocity, cadence, timing symmetry, smoothness, double support percent, etc.
- Variability
- Chair transfer
 - Root mean square (RMS) duration, range of motion, etc.
- Vehicle transfer

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 RMS, duration, peak angular velocity, etc.





AC Change Features

Percent change

$$- x_{\Delta\%} = \frac{x_{S2} - x_{S1}}{x_{S1}}$$

 Standardized mean difference effect size for repeated measures

$$- d_{RM} = \frac{\bar{X}_{post} - \bar{X}_{pre}}{S_D} [\text{Viechtbauer, 2007}] \\ - d_{RM} \pm CS * \hat{\sigma}_d^{2(L1)}, \hat{\sigma}_d^{2(L1)} = \sqrt{\frac{2(1-\hat{\rho})}{n} + \frac{d_{RM}^2}{2(n-1)}}$$

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[Wolff Smith and Beretvas, 2009]

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Supervised Models

 Train prediction models M₁ (admission), M₂ (AC S1), and M₃ (AC S2)



- Linear SVM, linear regression, random forest w/100 trees
- Evaluation

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Mean absolute error (MAE), root mean squared error (RMSE), normalized RMSE, and correlations

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Association for

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Model Approaches



Discharge FIM Motor Prediction

		Linear SVM			Linear Regression			Random Forest		
	Model	RMSE	NRMSE	r	RMSE	NRMSE	r	RMSE	NRMSE	r
Mı	M ₁ (w/o NAC)	4.66	11.65%	0.89**	6.07	15.19%	0.87**	8.14	20.36%	0.61**
	\mathbf{M}_1	7.36	18.41%	0.82**	7.95	19.87%	0.80**	10.86	27.14%	0.73**
	M2	8.55	21.38%	0.60*	9.82	24.55%	0.55*	10.18	25.45%	0.25
Sanarata	M_3	5.54	13.86%	0.85**	5.43	13.57%	0.86**	10.70	26.76%	0.07
Sepurule	M_{avg}	5.54	13.86%	0.87**	5.27	13.18%	0.89**	8.04	20.09%	0.69**
	M_E	5.50	13.74%	0.84**	5.69	14.22%	0.84**	9.38	23.46%	0.44
	M_2	5.49	13.71%	0.85**	5.88	14.69%	0.85**	8.51	21.27%	0.59*
Cumulative	M_3	2.32	5.80%	0.97**†	2.60	6.50%	0.97**†	9.78	24.46%	0.31
eunnuunre	M_{avg}	4.00	10.01%	0.94**†	4.05	10.12%	0.94**†	7.38	18.46%	0.77**†
	$M_{\rm E}$	3.41	8.53%	0.95**†	2.90	7.26%	0.96**†	9.30	23.24%	0.45*

avg = average, E = ensemble, M = model, NAC = non-ambulatory circuit, NRMSE = normalized root mean square error, r = Pearson correlation coefficient, RMSE = root mean square error, SVM = support vector machine, * = p < 0.05, ** = p < 0.01, † = significantly (p < 0.05) improved results from M₁.

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Discharge FIM Cognitive Prediction

		Linear SVM			Linear Regression			Random Forest		
	Model	RMSE	NRMSE	r	RMSE	NRMSE	r	RMSE	NRMSE	r
M ₁	M ₁ (w/o NAC)	2.42	20.19%	0.70**	2.50	20.86%	0.67**	2.61	21.72%	0.64**
	M1	2.34	19.49%	0.73**	2.56	21.30%	0.73**	2.36	19.69%	0.73**
	M ₂	3.10	25.82%	0.51*	5.50	45.81%	0.17	3.80	31.7%	-0.09
Separate	M3	3.74	31.17%	-0.34	3.61	30.11%	-0.23	4.15	34.57%	-0.12
Sepurate	Mavg	2.56	21.36%	0.68**	3.06	25.52%	0.45*	2.93	24.40%	0.52*
	M_E	2.66	22.14%	0.64**	3.09	25.77%	0.56*	2.87	RMSENRMSE r 2.6121.72%0.64**2.3619.69%0.73**3.8031.7%-0.094.1534.57%-0.122.9324.40%0.52*2.8723.92%0.53*3.7731.45%0.152.6121.72%0.64**2.4720.56%0.68**2.4620.52%0.68**	
	M ₂	3.44	28.69%	0.19	3.13	26.08%	0.37*	3.77	31.45%	0.15
Cumulative	M ₃	2.42	20.19%	0.70**	2.50	20.86%	0.67**	2.61	21.72%	0.64**
cumulante	Mavg	2.40	20.01%	0.73**	2.32	19.34%	0.74**	2.47	20.56%	0.68**
	M_E	2.71	22.59%	0.59*	1.48	12.36%	0.90**†	2.46	20.52%	0.68**

avg = average, E = ensemble, M = model, NAC = non-ambulatory circuit, NRMSE = normalized root mean square error, r = Pearson correlation coefficient, RMSE = root mean square error, SVM = support vector machine, * = p < 0.05, ** = p < 0.01, † = significantly (p < 0.05) improved results from M₁.

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Individual FIM Tasks



Individual Patient Prediction



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Clinical Utility of FIM Predictions

- 7 Physical therapists interviewed
- 7/7 are interested in using wearable technologies for their patients
- 6/7 said they would make use of FIM predictions for patients mid-stay
 - "It would be very useful, it could help with discharge planning if we needed to steer one way or another."

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What's Next?

- Increase sample size
 - Enough participants \rightarrow condition-specific models
 - Investigate the effects of comorbidities
- Mobile app!

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Online collection, processing, and prediction

Association for Computing Machinery

- Advanced machine learning techniques
- Adding sensor-based cognitive features

Thank You!

- Questions?
- Connect with me
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- Related publications



- G. Sprint, D. Cook, D. Weeks, and V. Borisov. <u>Predicting Functional</u> <u>Independence Measure Scores During Rehabilitation with Wearable Inertial</u> <u>Sensors</u>. IEEE Access, 2015.
- G. Sprint, D. Cook, and D. Weeks. <u>Towards Automating Clinical Assessments:</u> <u>A Survey of the Timed Up and Go (TUG)</u>. IEEE Reviews in Biomedical Engineering, 2015.
- G. Sprint, V. Borisov, D. Cook, and D. Weeks. <u>Wearable Sensors in Ecological</u> <u>Rehabilitation Environments</u>. ACM International Joint Conference on Pervasive and Ubiquitous Computing: Adjunct Publication, 2014.

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