

# A Machine Learning Approach to Sleep Quality Prediction for Inpatient Rehabilitation

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OVERVIEW

DATA COLLECTION

PREDICTION MODEL

RESULTS

CONCLUSIONS

**ACTIGRAPHS** are wearable sensors used to collect activity and sleep time series data. Our approach utilizes similarities among historical sequences of data to train machine learning algorithms to predict nighttime sleep duration for **STROKE** and **TRAUMATIC BRAIN INJURY (TBI)** patients during rehabilitation. Our approach is suitable for point-of-care and remote monitoring to detect changes in sleep for individuals recovering from stroke and TBIs.

- MOTIONLOGGER** Actigraph watches, by Ambulatory Monitoring, Inc
- 17 TBI and stroke patients
- 7+ days of data per patient
- MINUTE-BY-MINUTE** activity data collected **24 HOURS** per day

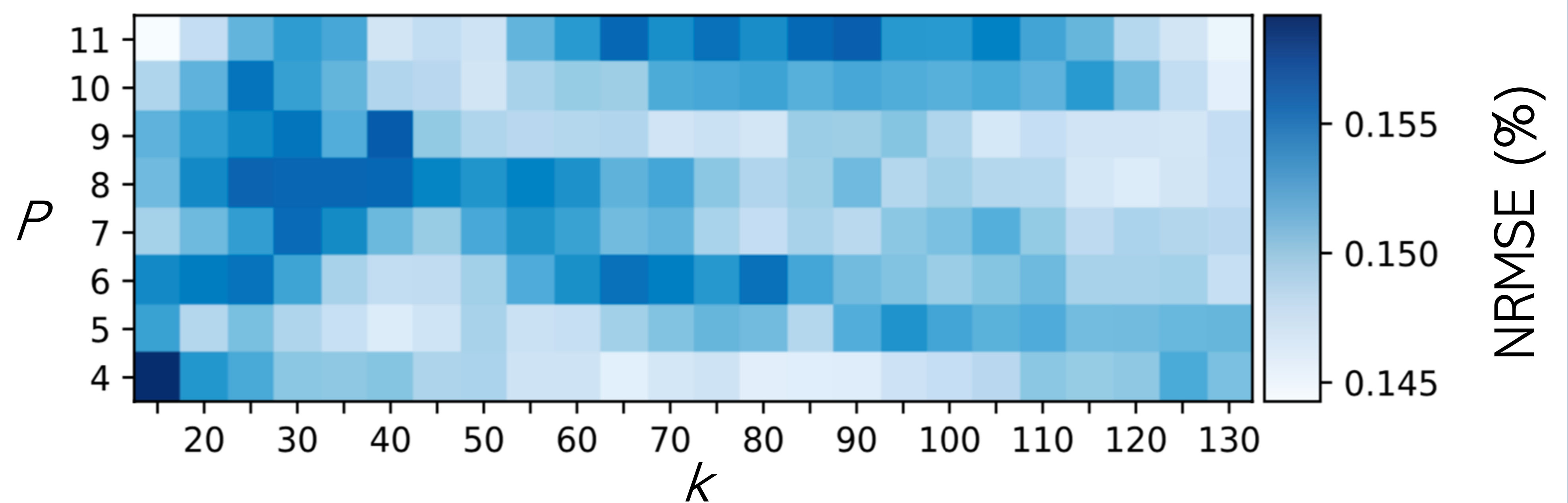
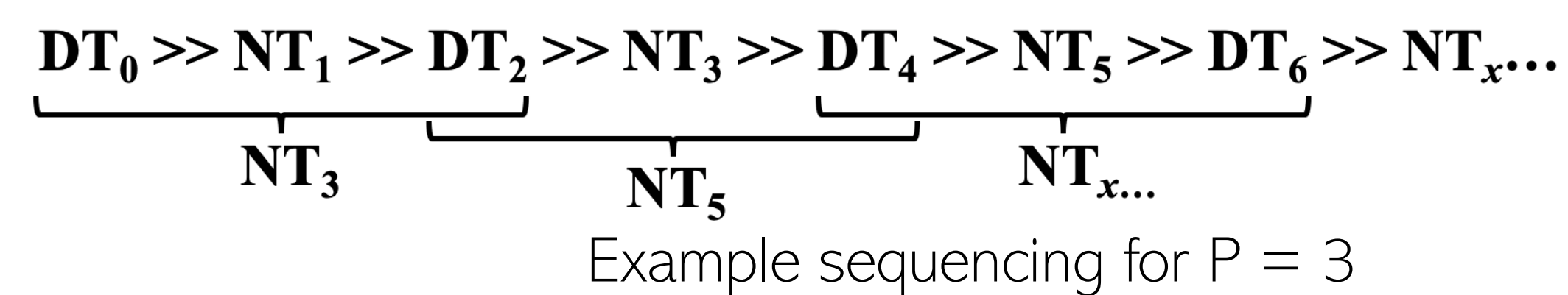
## DAYTIME (DT) FEATURES

DAYTIME ACTIVITY RATIO (DAR)  
MEAN ACTIVITY COUNT  
MEDIAN ACTIVITY COUNT  
ACTIVITY COUNT STD DEVIATION

## NIGHTTIME (NT) FEATURES

TOTAL SLEEP TIME (TST)      LONGEST SLEEP BOUT  
SLEEP EFFICIENCY              MEAN SLEEP BOUT  
SLEEP ONSET LATENCY         SLEEP TRANSITIONS  
WAKE AFTER SLEEP ONSET      AROUSAL INDEX

- k-NEAREST NEIGHBORS (KNN)** model was used to identify  $k$  similar Actigraphy sequences based on DT and NT features during preceding periods
- RANDOM FOREST REGRESSION** was used to predict the total nighttime sleep duration based on similar sequences
- $P$  denotes the number of preceding periods used to formulate predictions



## TOP NT TOTAL SLEEP TIME PREDICTION RESULTS

MODEL	$P$	$K$	NRMSE
RF <sub>LOOCV</sub>	11	[all sequences]	14.40%
RF <sub>KNN</sub>	11	15	14.43%
RF <sub>KNN</sub>	11	130	14.51%
RF <sub>KNN</sub>	10	130	14.56%
RF <sub>KNN</sub>	11	40	14.69%

By tuning parameters related to our regression algorithm, we obtained a **NORMALIZED ROOT MEAN SQUARE ERROR** of **14.40%**. Through experimentation, **WE FOUND THE OPTIMAL  $P$  VALUE TO BE 11 PERIODS**, which is the maximum value of  $P$  for this dataset. To elaborate, this means that each training sample consisted of the features from six DT periods ( $DT_0, DT_2, DT_4, DT_6, DT_8, DT_{10}$ ) and five NT periods ( $NT_1, NT_3, NT_5, NT_7, NT_9$ ), which were used to predict TST during  $NT_{11}$ . The poorest performing  $P$  values included  $P=\{1, 2, 3\}$ . These were excluded from the heat map above to elucidate the patterns of the larger  $P$  values. These results suggest **LONGER SAMPLES CAN IMPROVE ACCURACY**. They also demonstrate that similar results can be obtained with lower  $P$  values if  $k$  is increased to compensate.